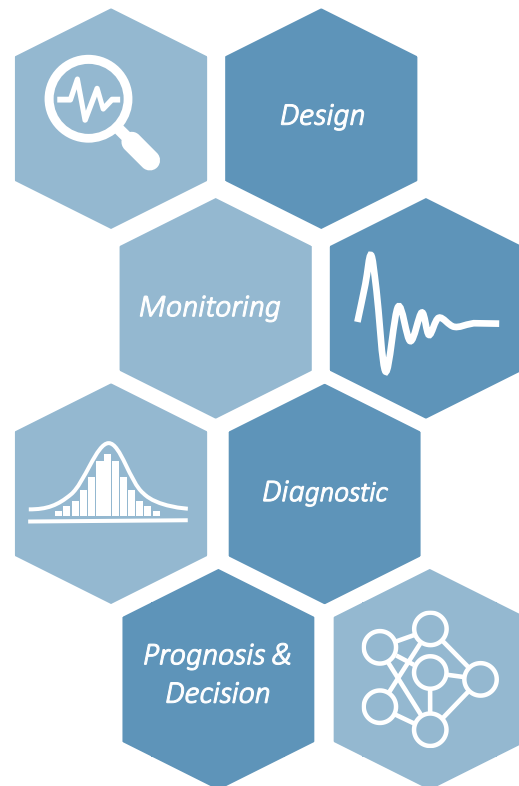


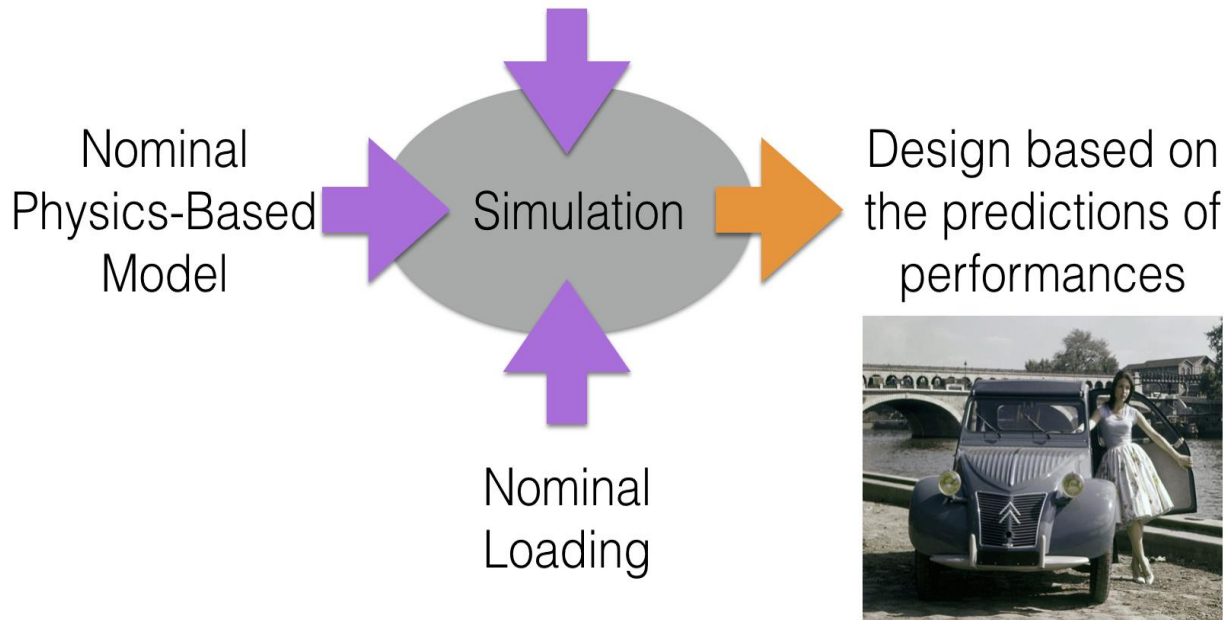
Jumeaux numériques : généalogie, anatomie, physiologie et éthique



Francisco (Paco) CHINESTA
Francisco.Chinesta@ensam.eu

Performances in designs

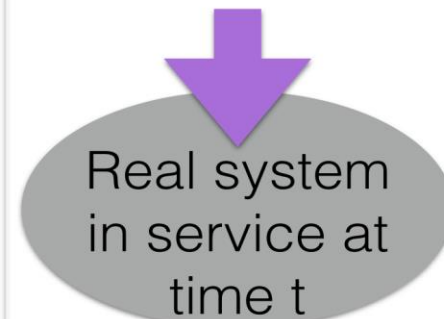
Few Data for Model Calibration



Performances in operation

Real load

$$\tau \leq t$$



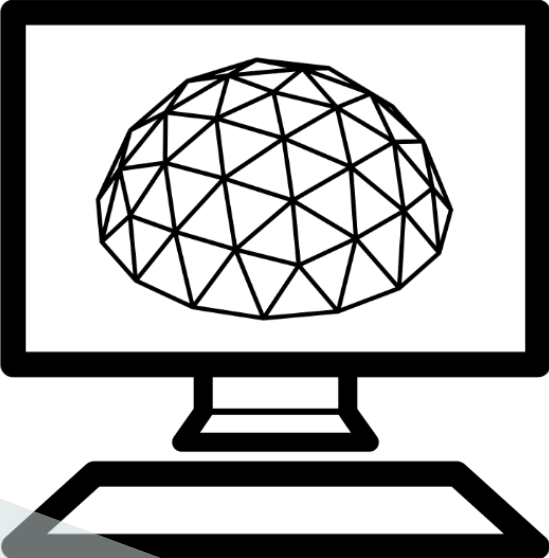
Prediction $\tau \geq t$

World is changing. Today we do not sell aircraft engines, but hours of flight, we do not sell electric drills but good quality holes, ... We are nowadays more concerned by the performance management than by the products themselves ...

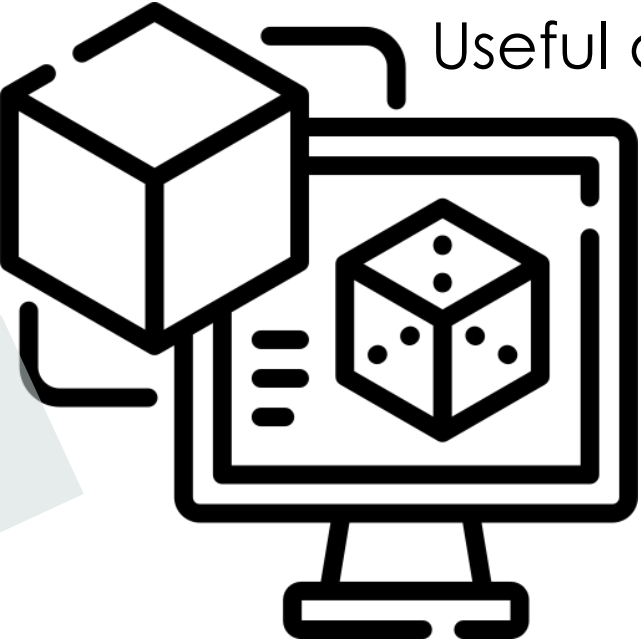


**PREDICTING
FAST & WELL**

INTRODUCTION: three levels of digitalization as proposed by Charbel FARHAT



Physical asset (or process)

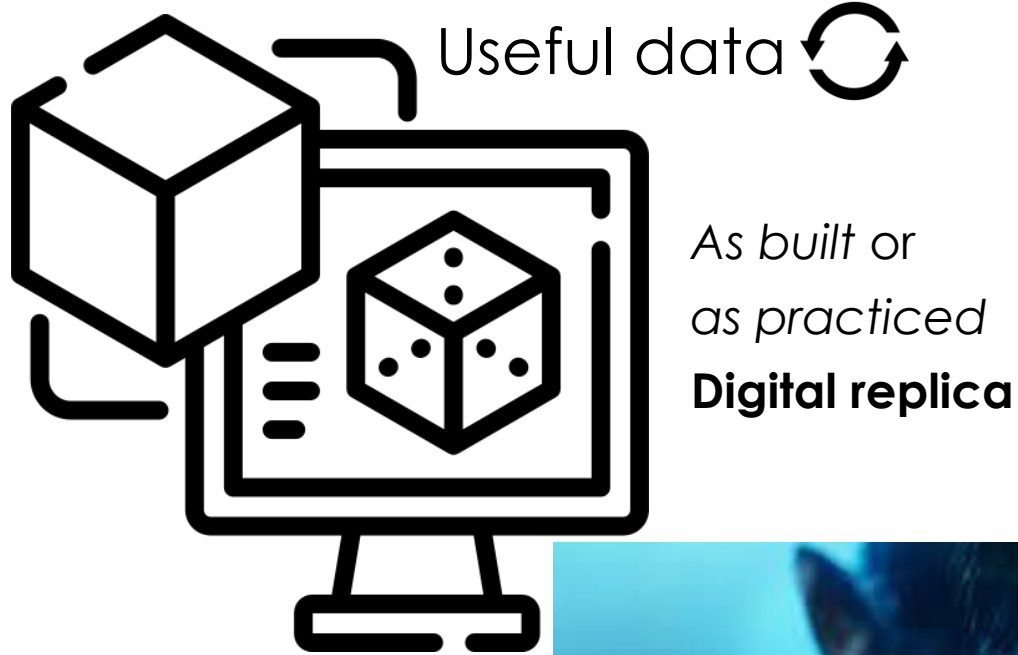


Useful data 

*As built or
as practiced*
Digital replica



Physical asset (or process)

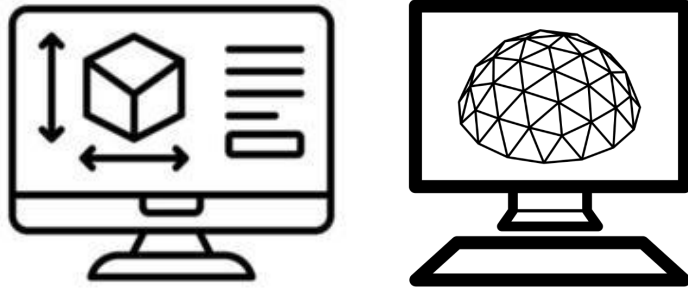


Based on:

- the best available multi-physics, multiscale & probabilistic computational models
- sensor information

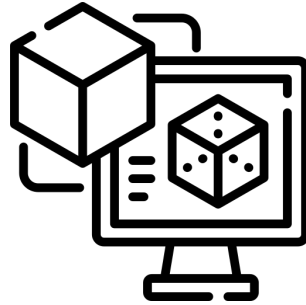
To mirror & predict the functioning and performances over the life cycle of the associated physical asset.

□ the digital twin prototype



designs, analyses and processes used to realize the physical product

□ the digital twin instance



digital twin of each individual instance of the product once it is manufactured

□ the digital twin aggregate



allows for a larger set of data to be collected and processed for interrogation about the physical product.

THE LIMITS OF THE EXISTING PARADIGMS

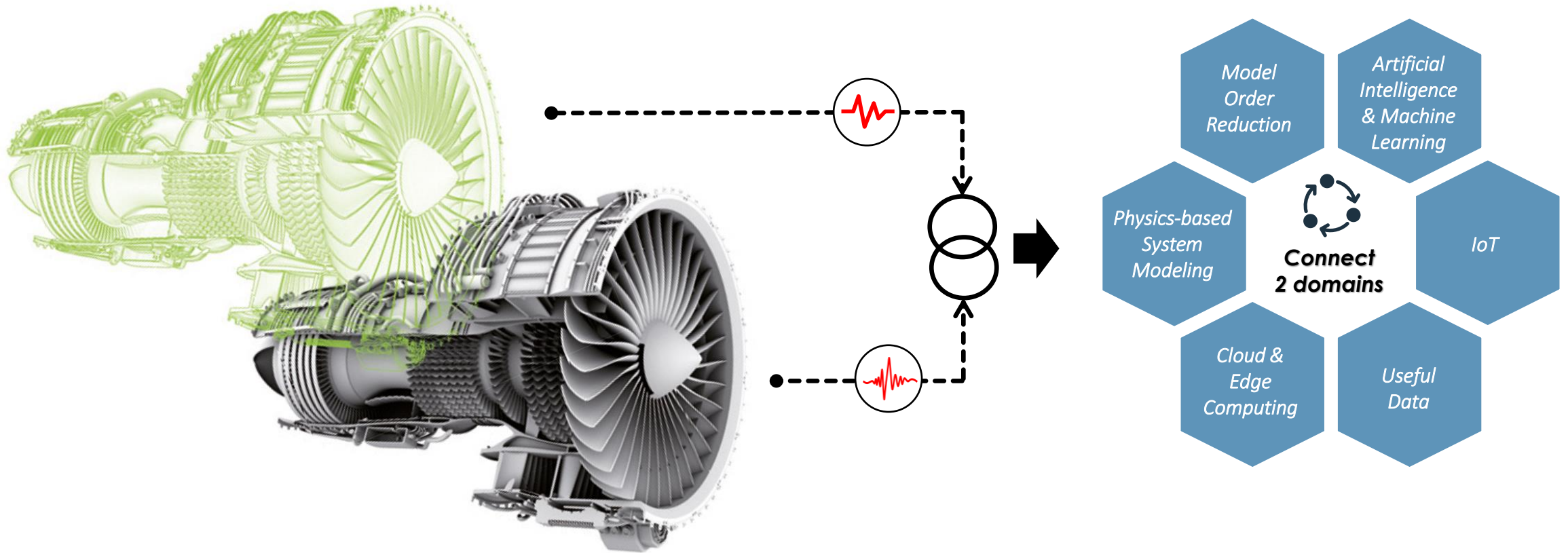


The usual simulation-based paradigm fails to perform diagnosis, prognosis and decision making when addressing complex systems of systems because of

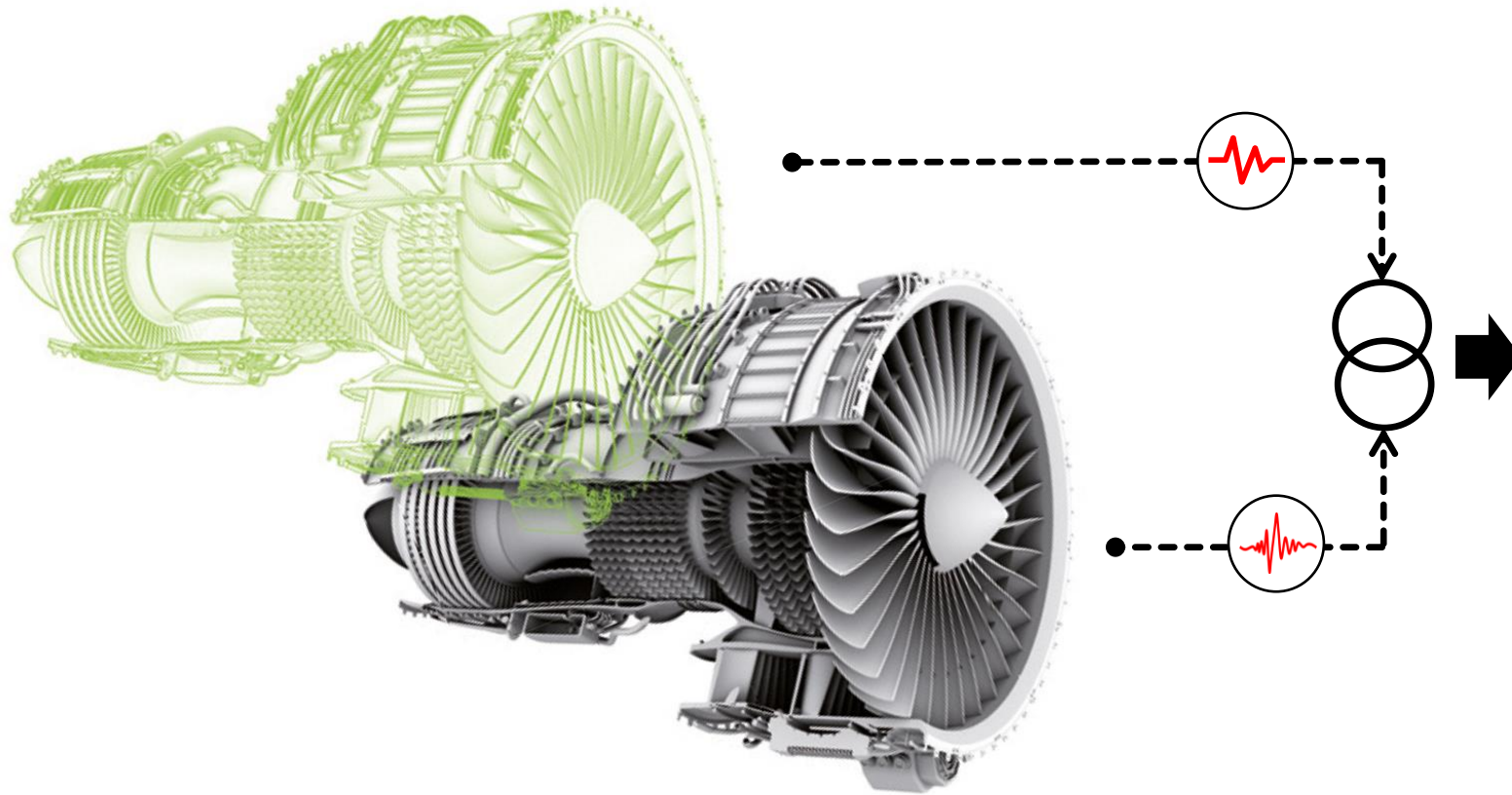
- **Physics-based:** the lack of fidelity of state-of-the-art models, and the lack of efficiency related to their solution procedures.
- **Data-driven:** the availability of data, its quality, as well as the limitations related to the extrapolation or the ability to explain the predictions offered by the trained models.

The **hybrid paradigm** conciliates both paradigms, knowledge and data enrich mutually, reducing the amount of data, driving their collection, enabling explaining and certifying predictions and decisions, accounting for human and societal interests and constraints.

Virtual representation of real-world entities and processes, synchronized at a specific frequency and fidelity throughout its lifecycle, and informs decisions that realize value



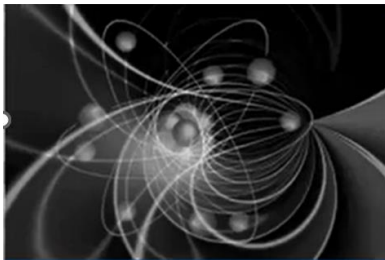
Virtual representation of real-world entities and processes, synchronized at a specific frequency and fidelity throughout its lifecycle, and informs decisions that realize value



Actionable Insights :

- Virtual Prototyping
- Testing & Validation
- Design Optimization
- Virtual Sensing (Monitoring)
- Predictive Model-Based Control
- Predictive Maintenance
-

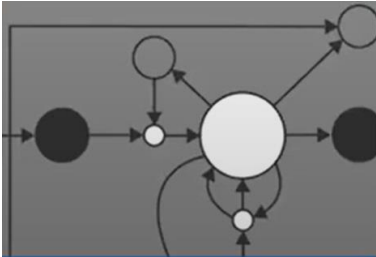
CONSTRAINTS



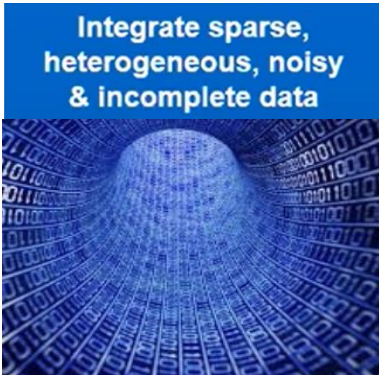
Respect physical constraints



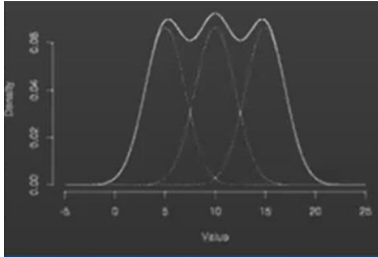
Embed domain knowledge



Bring interpretability to results



Integrate sparse, heterogeneous, noisy & incomplete data



Make predictions with quantified uncertainties



Support high-consequence decisions

The **hybrid paradigm** conciliates both paradigms, knowledge and data enrich mutually, reducing the amount of data, driving their collection, enabling explaining and certifying predictions and decisions, accounting for human and societal interests and constraints.



Reality = Knowledge + Ignorance

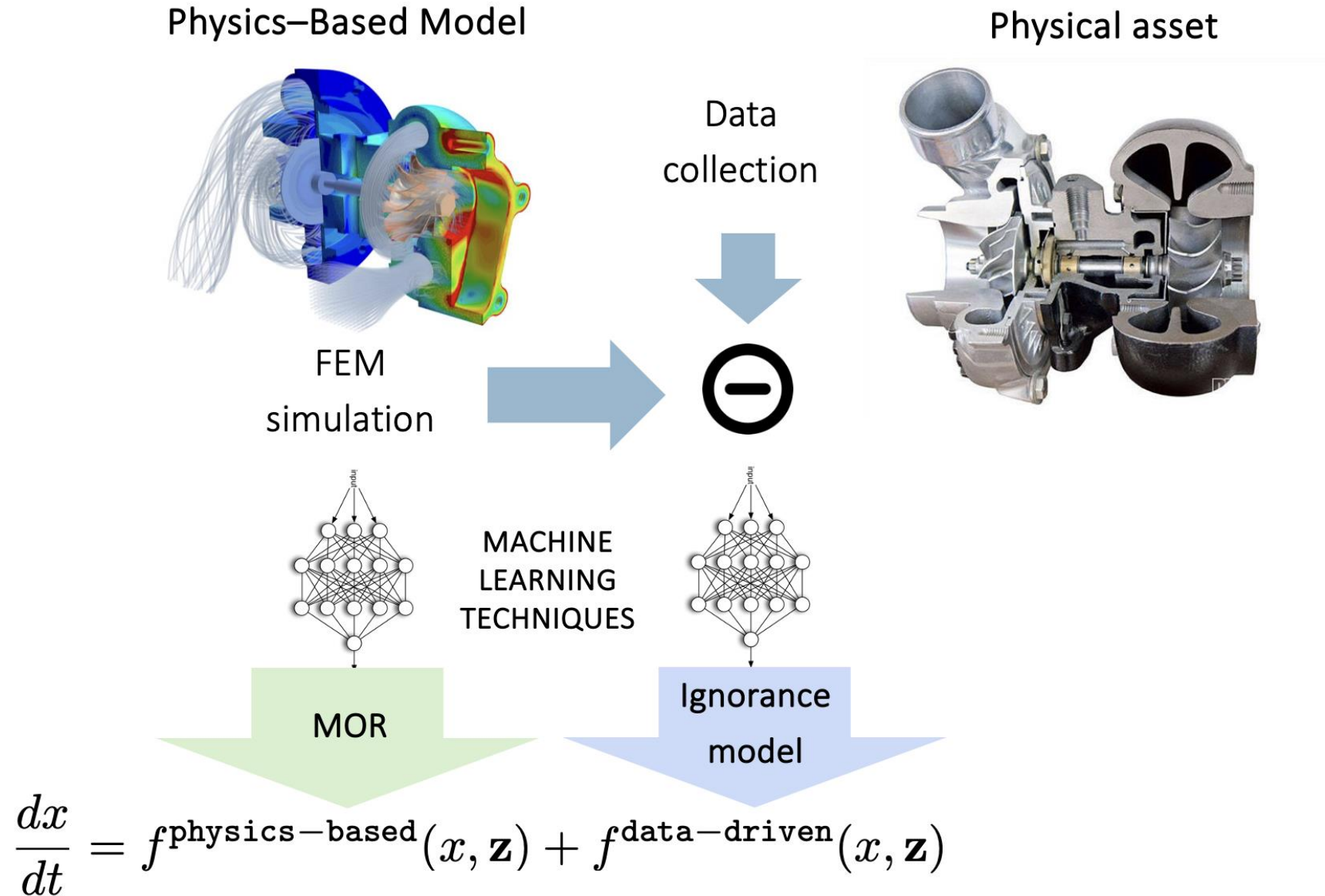
Physics-based

Data-driven

Real-time physics

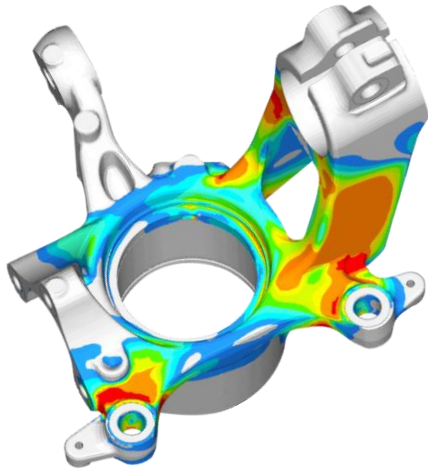
Real-time frugal ML

A SUCCESSFULLY APPLIED HAI TECHNOLOGY FOR PREDICTING FAST & WELL



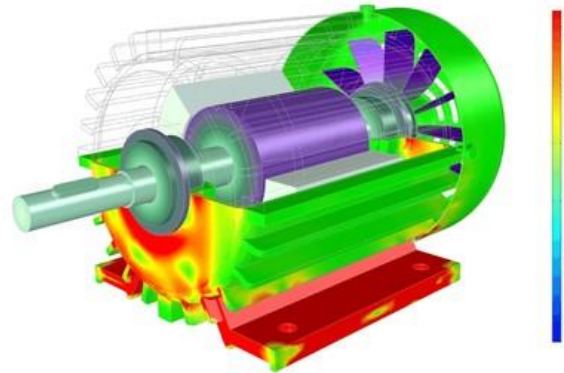
A representation of the universal governing laws of nature complemented with phenomenological behavior relationships

Linear & Nonlinear Elasticity



minutes, hours, ...

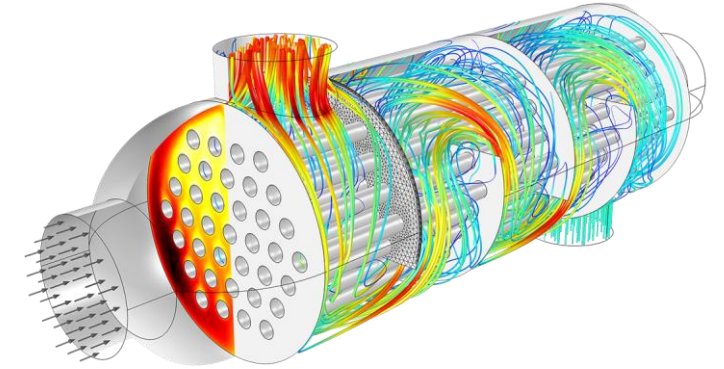
Electromagnetism & Acoustics



shutterstock.com · 2311455077

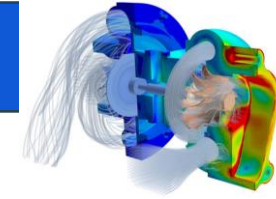
hours, days, ...

Fluid Dynamics



days, weeks, ...

- **Expensive but accurate**
- **Cheaper by using Model Order Reduction**



MOR/
Surrogate

$$\frac{dx}{dt} = f^{\text{physics-based}}(x, \mathbf{z}) + f^{\text{data-driven}}(x, \mathbf{z})$$

Active Learning

- Goal-oriented GP
- Extended Fisher Information
 - Tensor decompositions
 - Information surrogates

Data Reduction

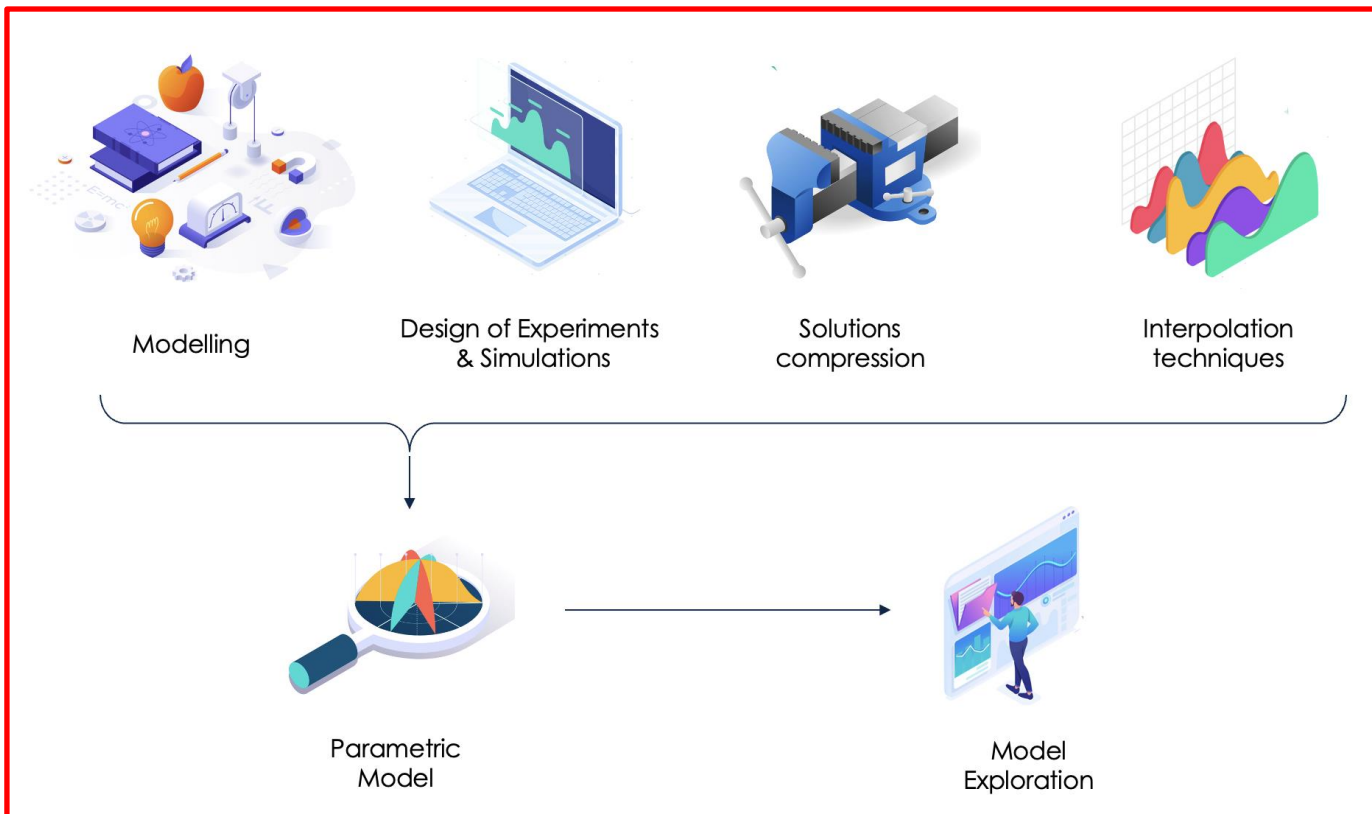
- Linear (PCA)
- Nonlinear:
 - Manifold learning
 - Autoencoders

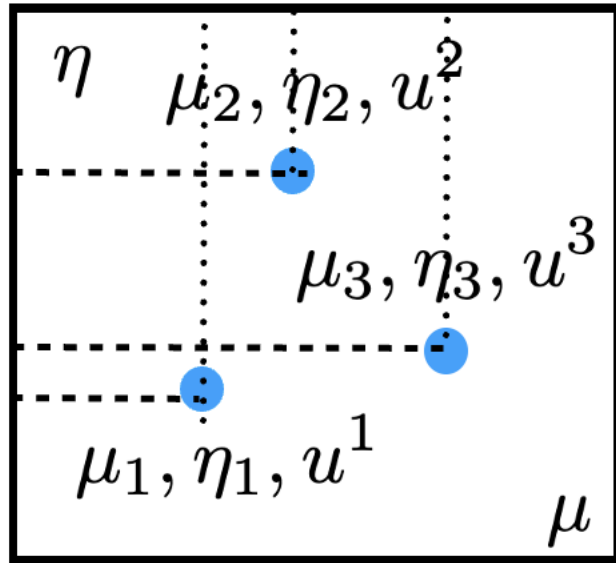
Regression (informed)

- Regularized Lineal Polynomial
 - Elastic Net, Ridge, Lasso, ...
- Nonlinear:
 - NN-based
 - Optimal transport

Postprocessing

- Data analytics
- Optimizers
- Uncertainty propagation
- Inversion / Data assimilation
- Control

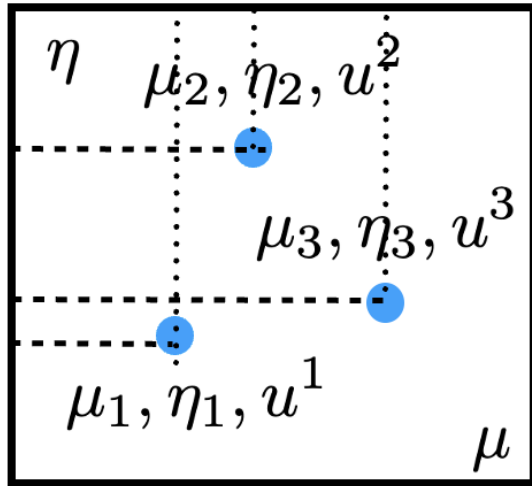




Linear regression

Linear approximation

$$u(\mu, \eta) = a + b\mu + c\eta$$

**SPARSE**

$$[1, \mu, \eta, \mu^2, \mu\eta, \eta^2, \mu^2\eta, \mu^2\eta^2, \mu\eta^2]$$

$$u(\mu, \eta) = \sum_{i=1}^N c_i \mathcal{F}_i(\mu, \eta)$$

$$N \gg 3$$

Regularization

$$\sum_{j=1}^3 \|u(\mu_j, \eta_j) - u^j\|_2^2 + \lambda \sum_{i=1}^N |c_i|$$

Physics-aware interaction between virtual and physical objects in Mixed Reality

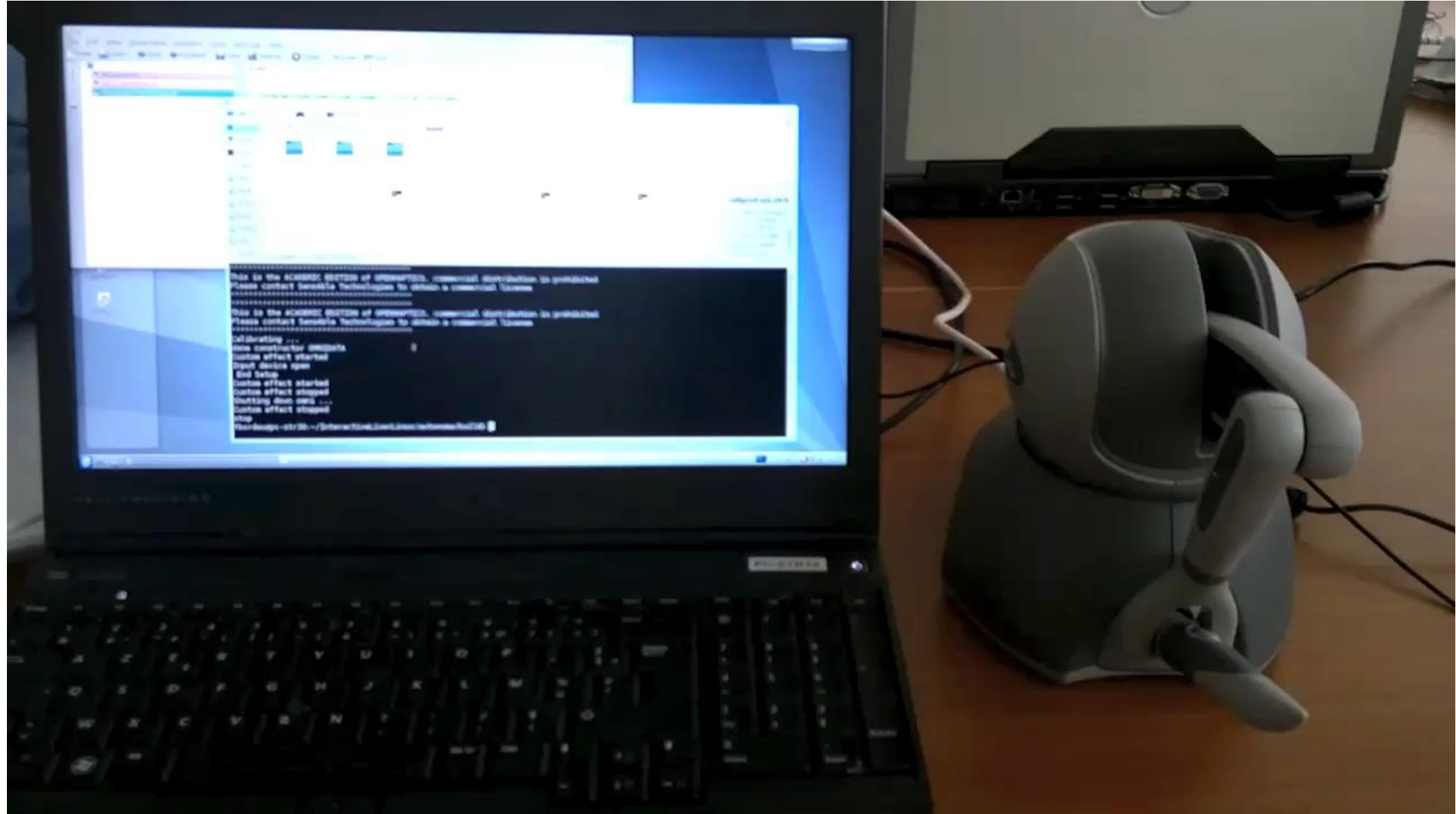
A. Badías, D. González, I. Alfaro, F. Chinesta, E. Cueto

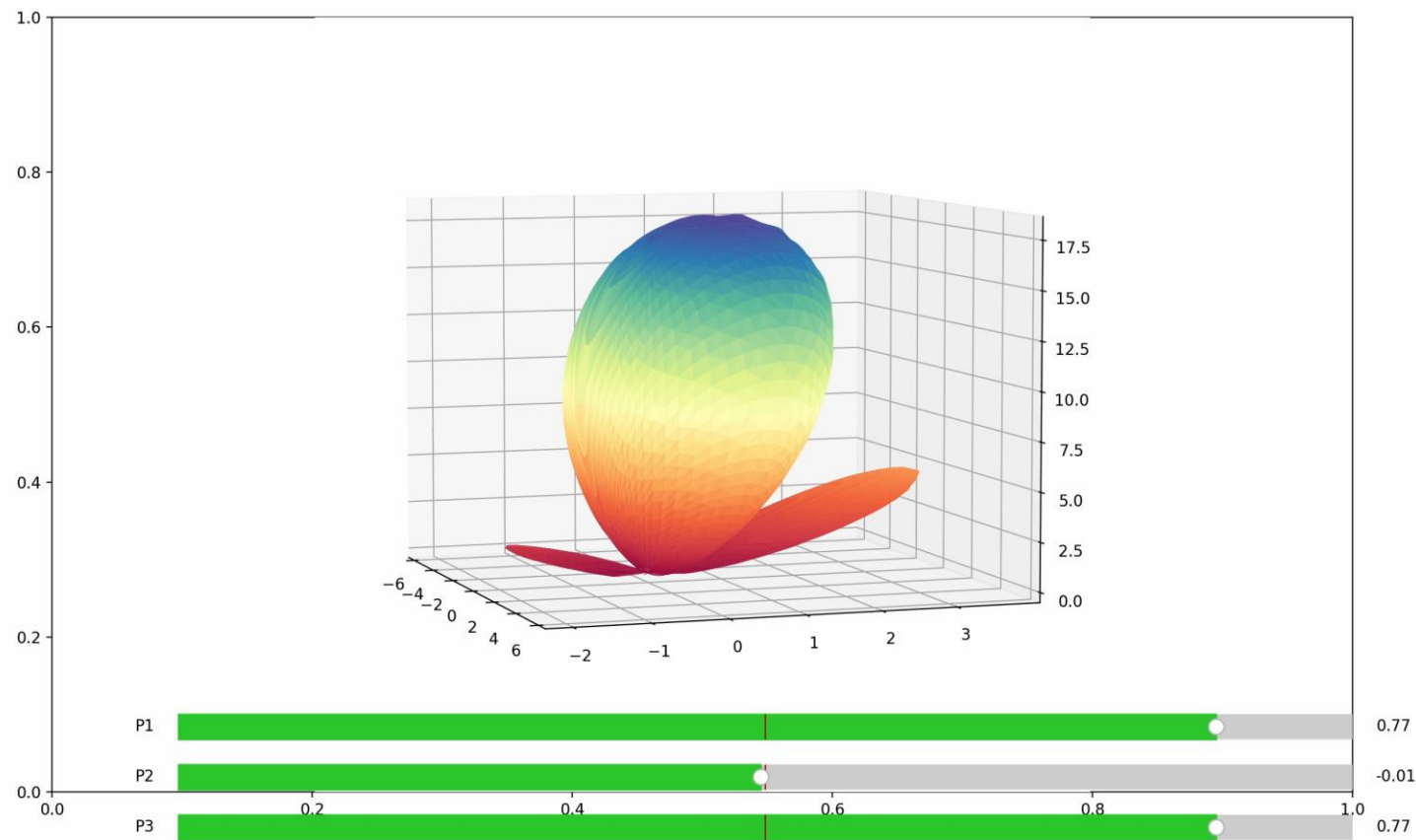
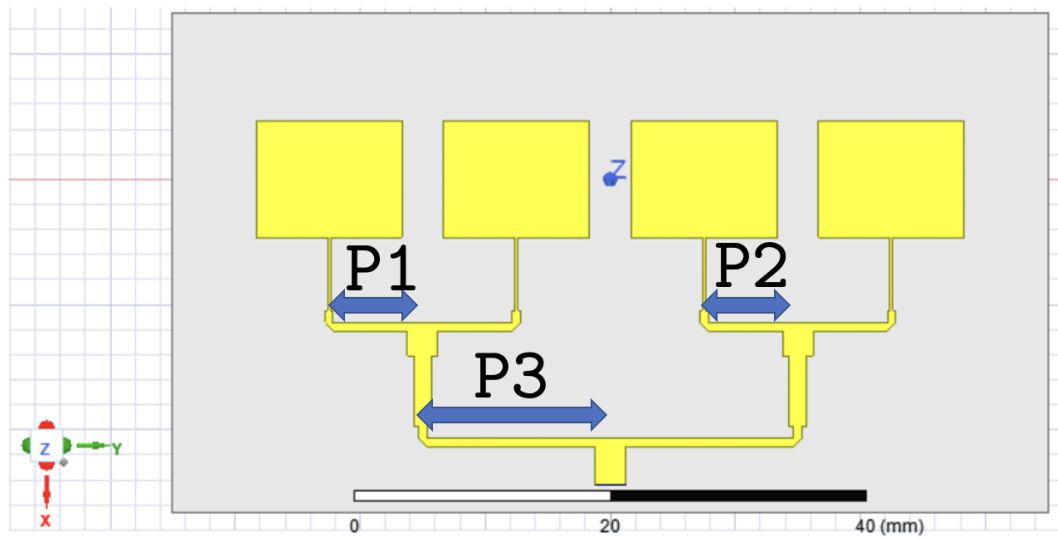


Universidad
Zaragoza

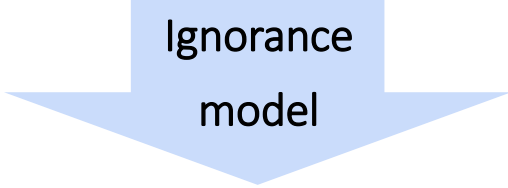
unizar.es


PHYSICS IN REAL TIME





Ignorance
model



$$\frac{dx}{dt} = f^{\text{physics-based}}(x, \mathbf{z}) + f^{\text{data-driven}}(x, \mathbf{z})$$


Regularized polynomial regressions, GP, DT, RF, SVR, ...

CNN

GNN

rNN, LSTM, ResNET, NeuralODE, DeepONet, Reservoir computing, Koopman...

GAN

Transformers

Autoencoders

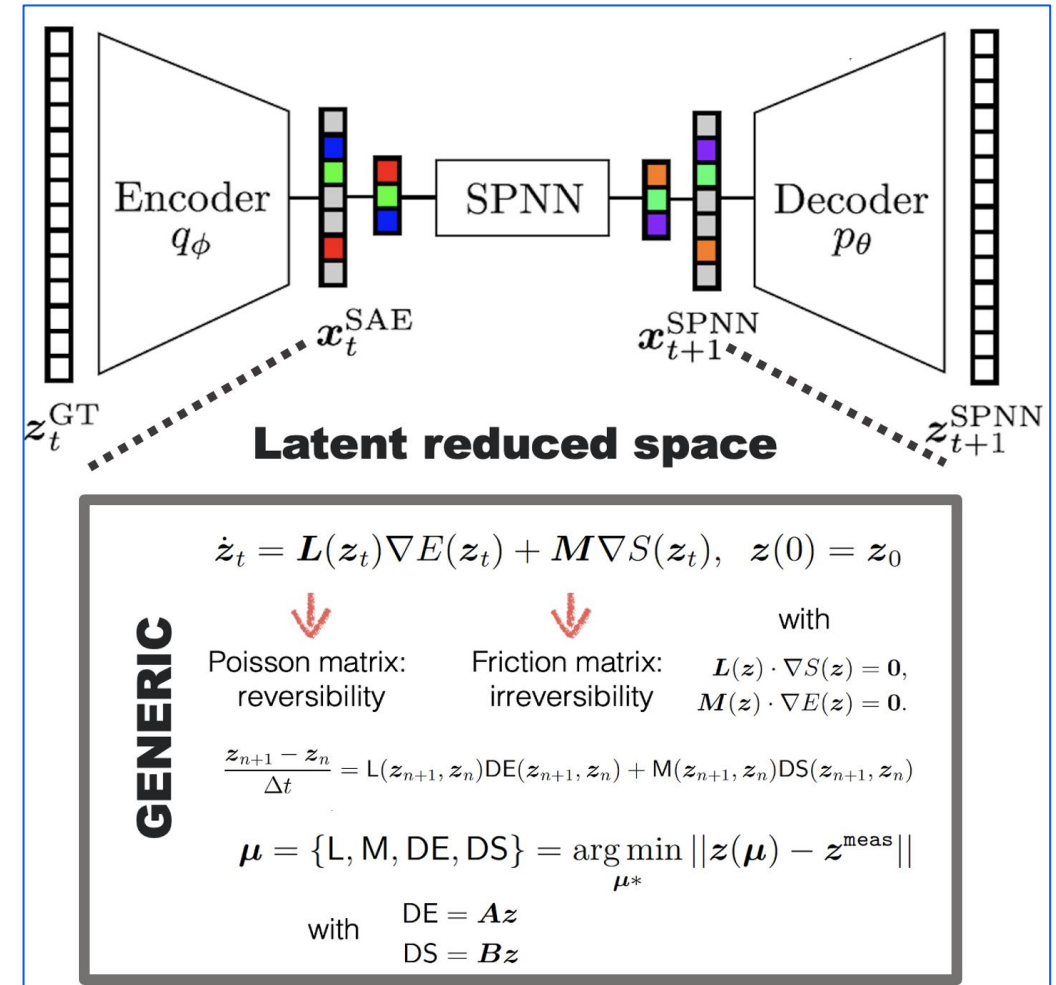
PINN, SPNN, PANN, ...

Ignorance
model

$$\frac{dx}{dt} = f^{\text{physics-based}}(x, \mathbf{z}) + f^{\text{data-driven}}(x, \mathbf{z})$$

Physically sound, self-learning digital twins for sloshing fluids

B. Moya, I. Alfaro, D. González, F. Chinesta, E. Cueto



I - MODEL ORDER REDUCTION: LEGO-LIKE & MULTI-TIME

II - RANK REDUCTION AUTOENCODERS / CONSTRAINTS IN THE LATENT SPACE

III - LEARNING PARSIMONIOUS PARAMETRIC (DYNAMICAL) MODELS

IV - LEARNING HIERARCHICAL MULTI-TIME MODELS

V - GENERATIVE AI for GENERATIVE DESIGN

VI - GRAPHS NN: SHM, MULTI-PHYSICS, T-GCN & EVOLVING GCN, ...

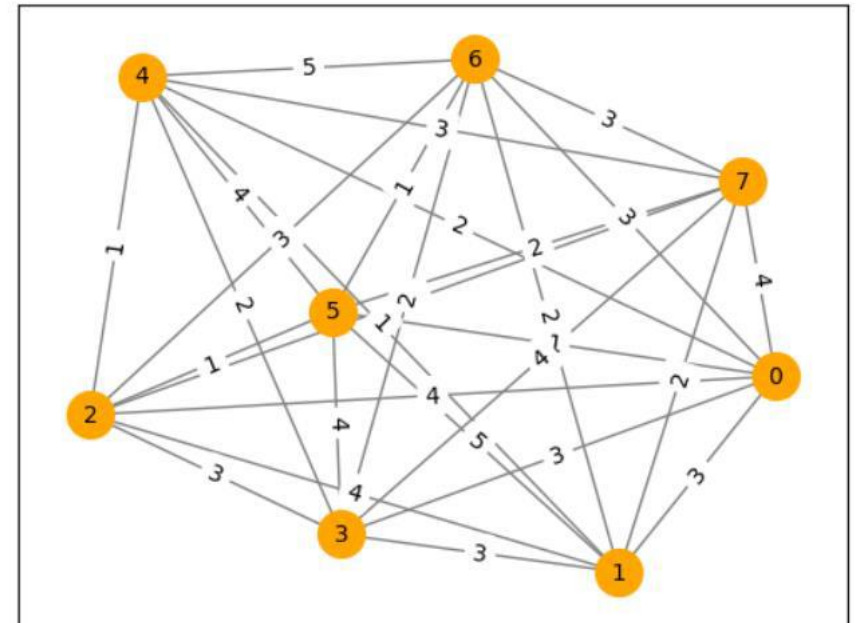
VII - INDUCTIVE BIASES

VIII - QUANTUM COMPUTING

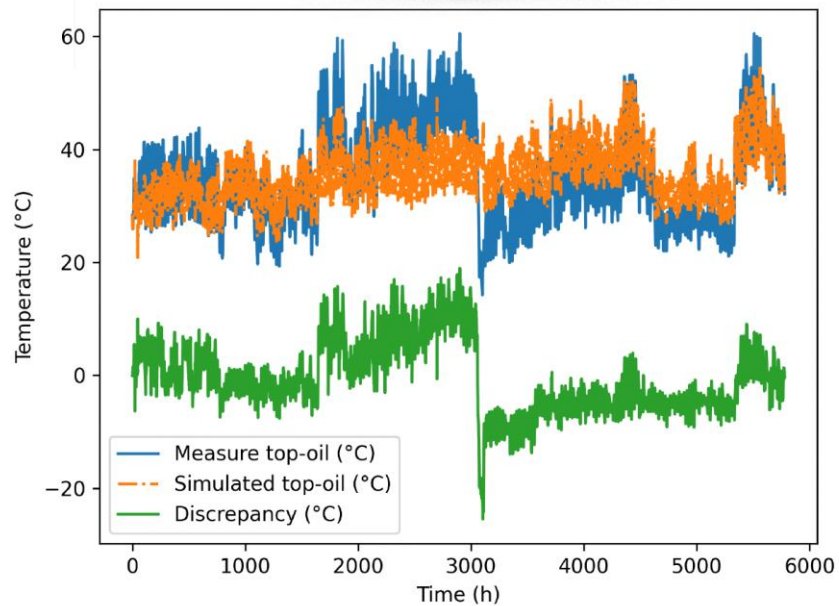
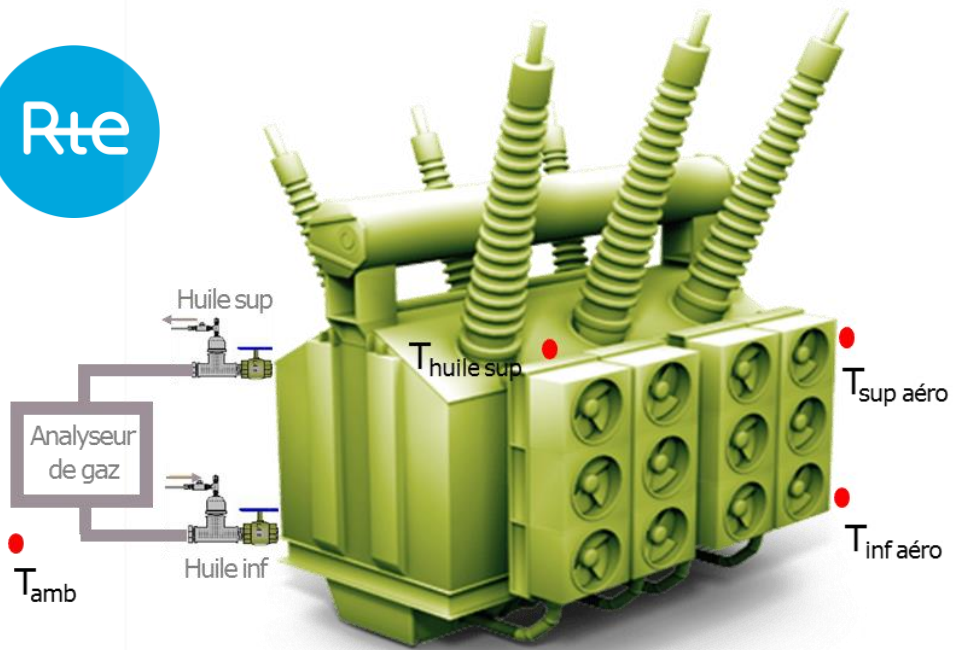
Quadratic Unconstrained Binary Optimization (QUBO)

$$\mathcal{H} = X^T Q X$$

& constraints

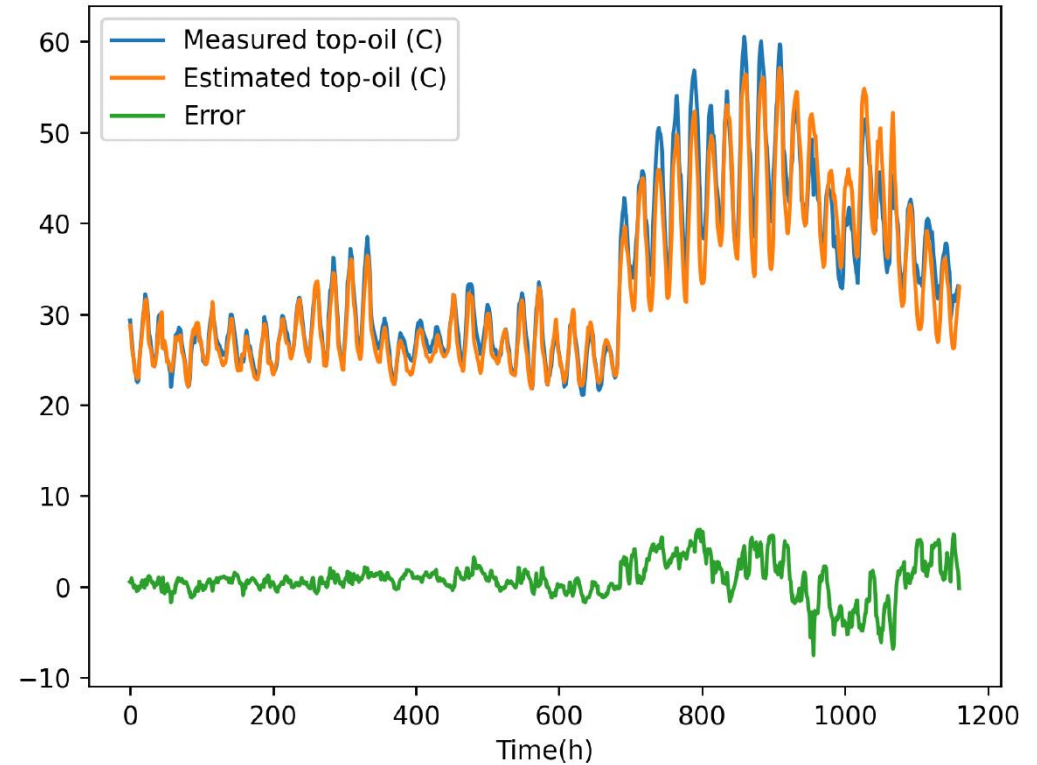


TRANSFORMER HYBRID TWIN INSTANCE

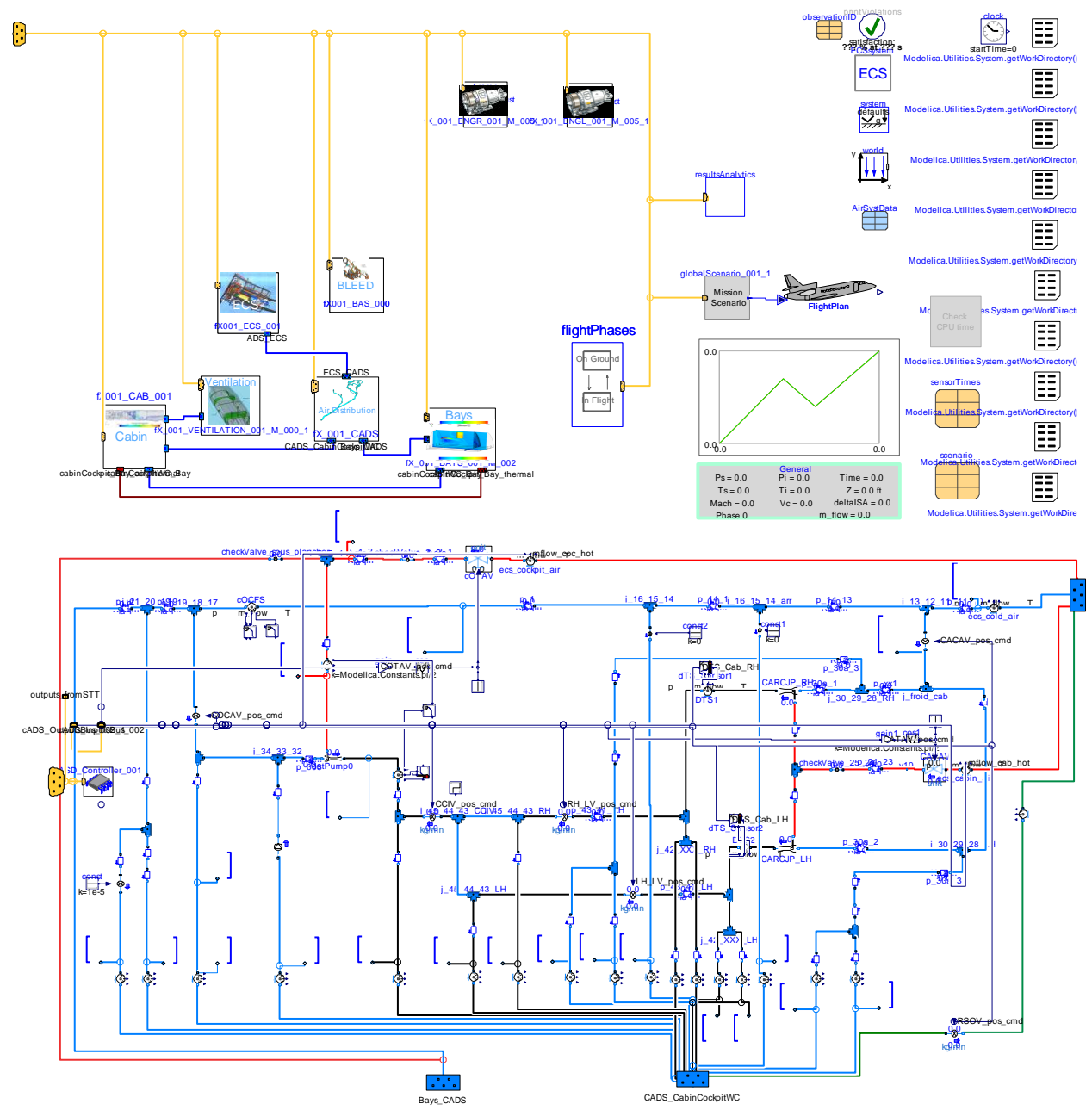
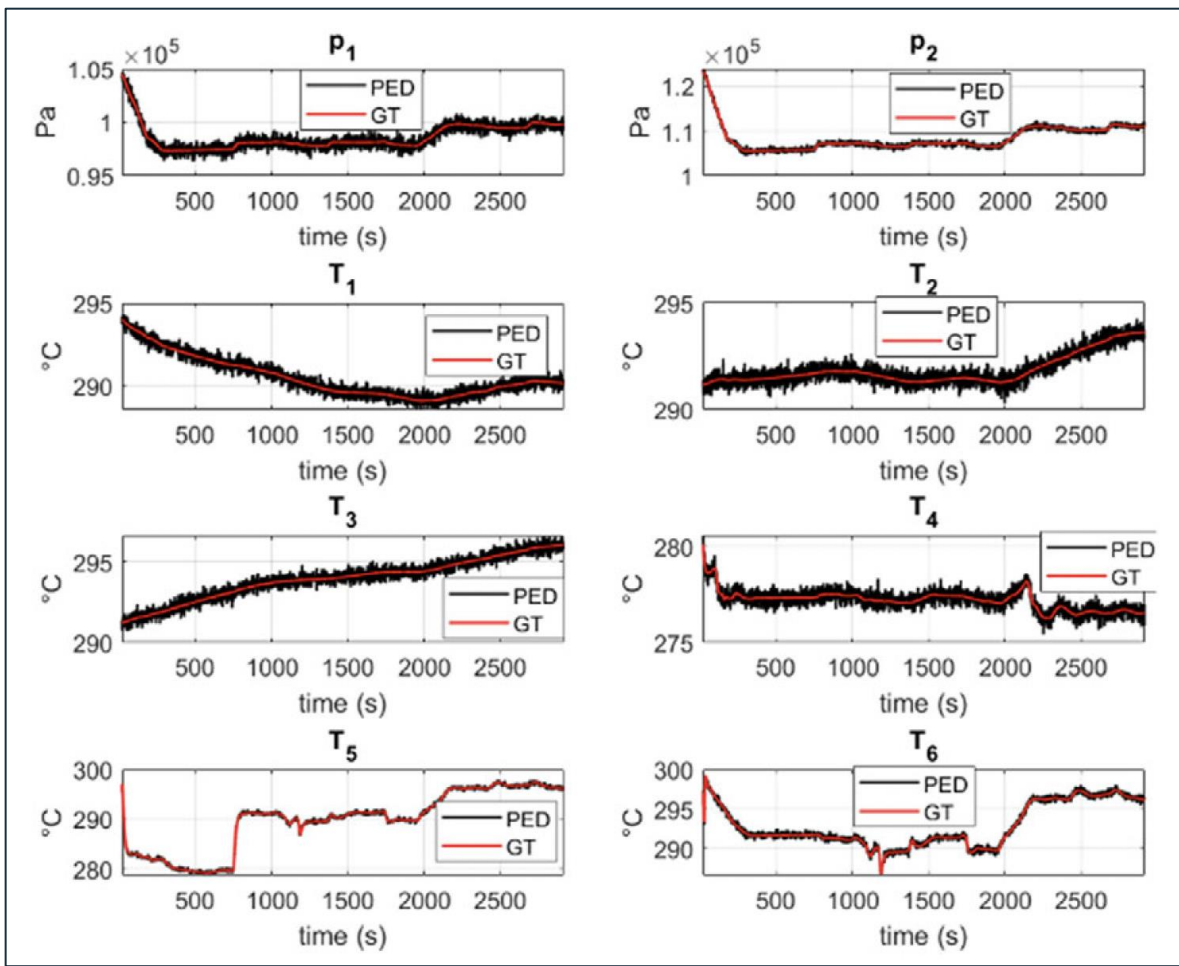
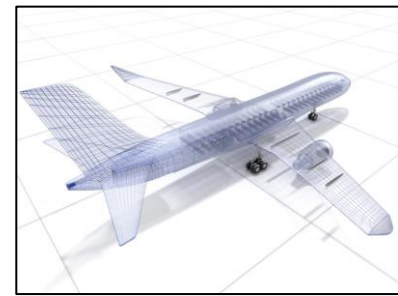


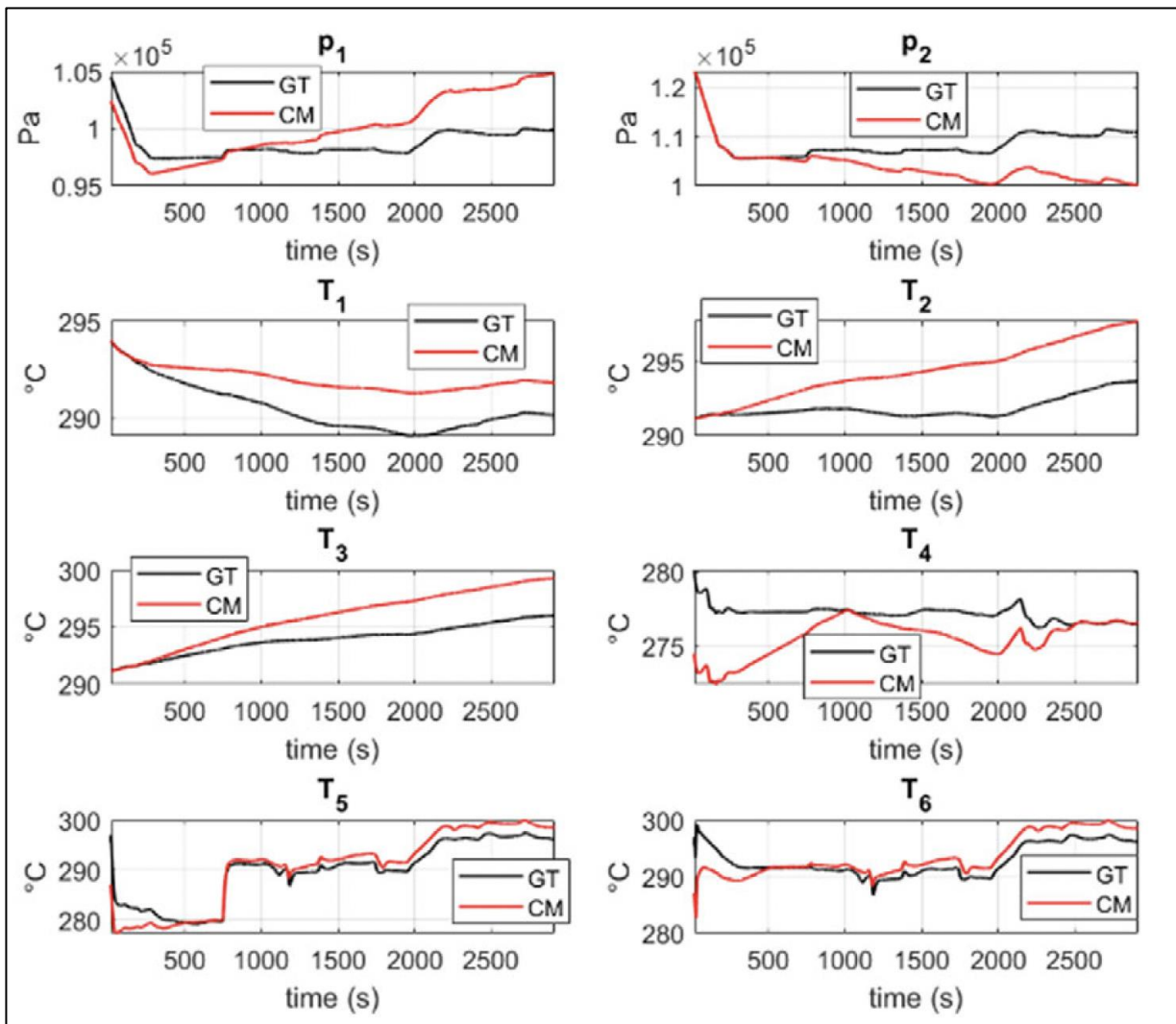
$$\frac{dx}{dt} = f^{\text{physics-based}}(x, \mathbf{z}) + f^{\text{data-driven}}(x, \mathbf{z})$$

Testing+integration: HT Oil temperature estimation for a RTE transformer

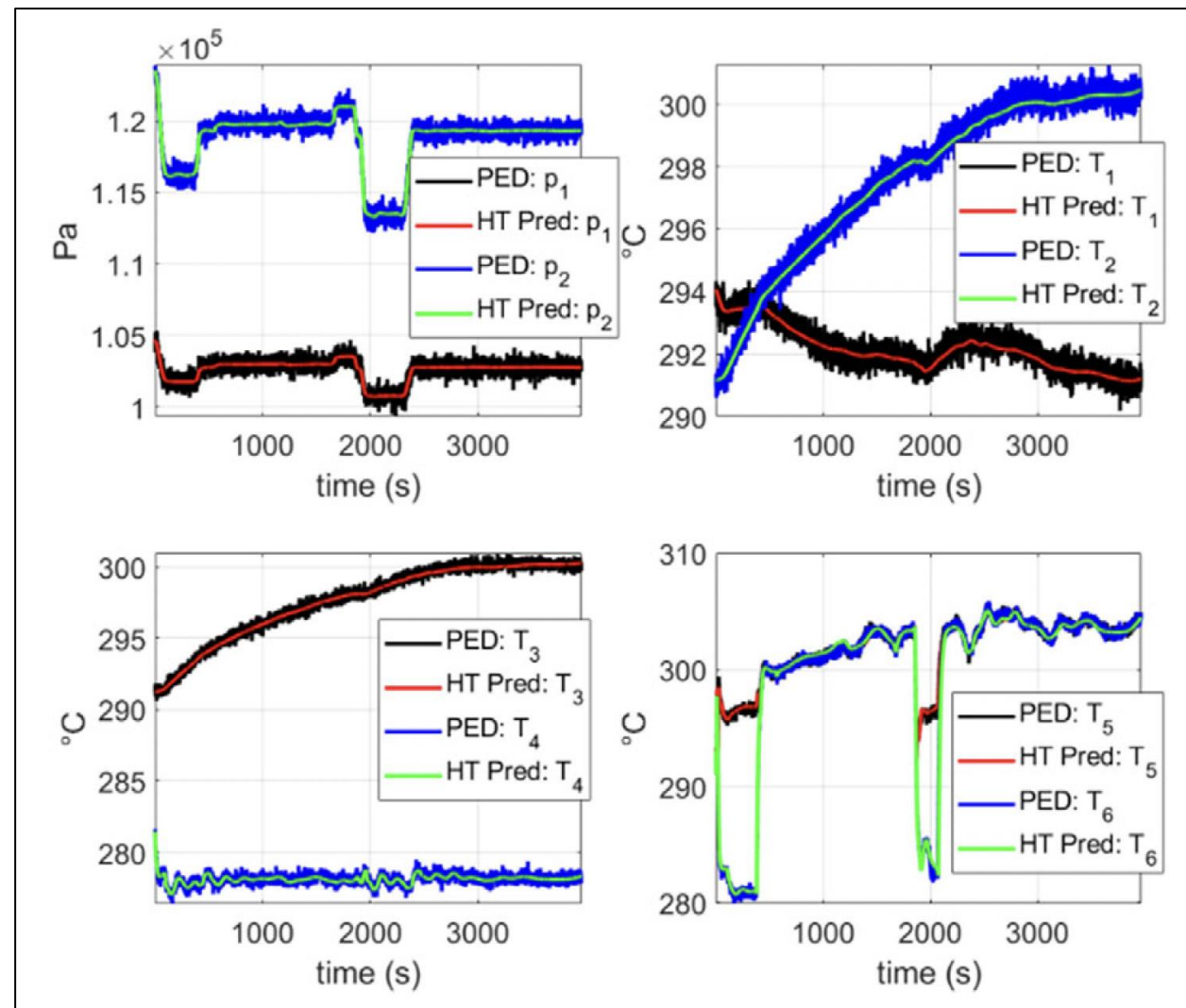


SYSTEM MODEL ENRICHMENT – HYBRID MODELLING





$$\frac{dx}{dt} = f^{\text{physics-based}}(x, \mathbf{z}) + f^{\text{data-driven}}(x, \mathbf{z})$$



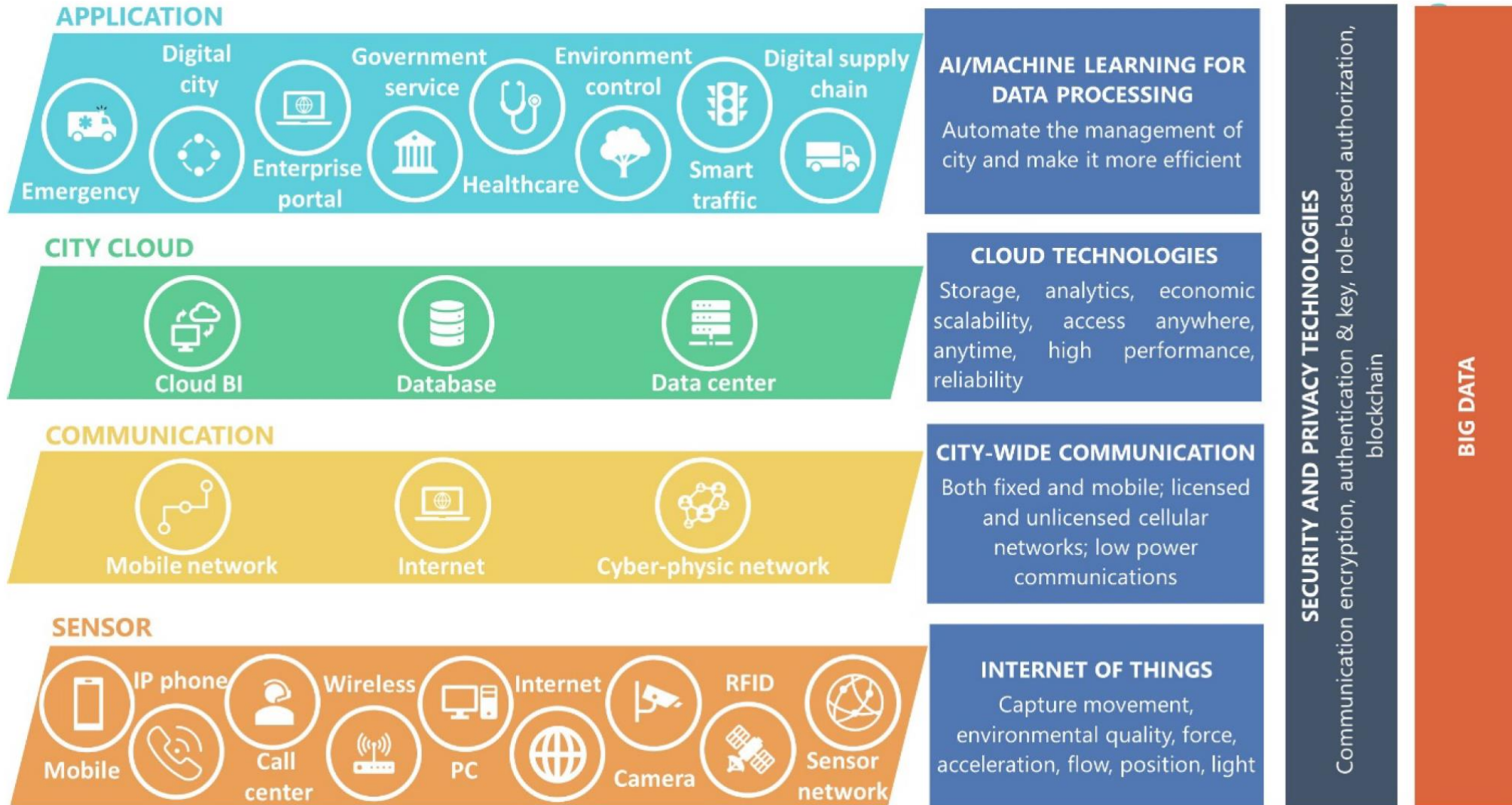


DesCartes

Intelligent modelling for decision making in critical urban systems



**NATIONAL
RESEARCH
FOUNDATION**





SECURITY



RESPONSIBILITY



ETHICS

Smart cities and territories constitute a complex system of systems, intimately entangled, contributing to the security, pleasure and comfort of citizens, and operating in a secure, responsible, ethical and transparent way.

City Digital Twin

technologies enabling digital twins of critical urban systems

THALES

AZUR
DRONES

NAVAL
GROUP

edf

[expleo]

esi
get it right

IMMERSION
IMAGINATION, INTERACTION ...

SKF®

suez

cetim

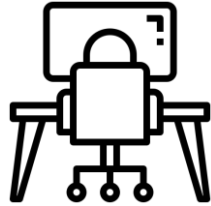
MATCOR
a cetim company

FLYING
WHALES

DesCartes

FROM RESEARCH TO APPLICATION

INFORMED PEOPLE / SERVICES



CONTROL TOWER
HYBRID TWIN
SYSTEM OF SYSTEMS



HYBRID TWINS
COMPONENTS & SUBSYSTEMS

KNOWLEDGE



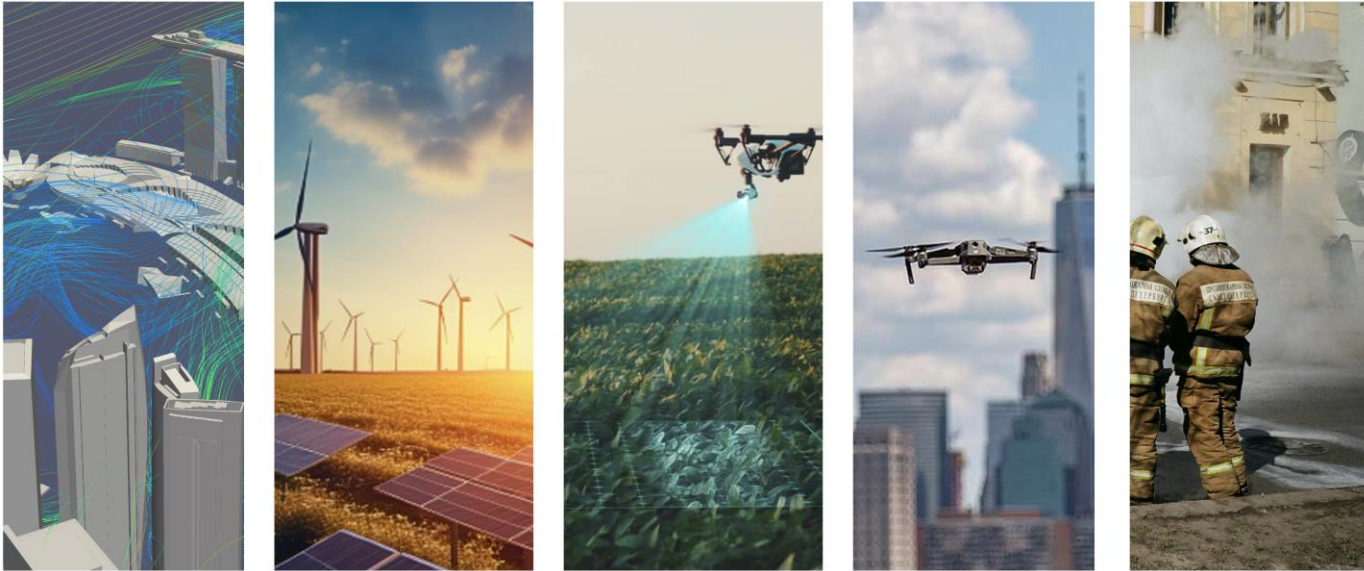
DATA

HAI BUILDER

IMPLEMENTABLE ALGORITHMS & METODOLOGIES

DESCARTES WORKPAGES RESEARCH

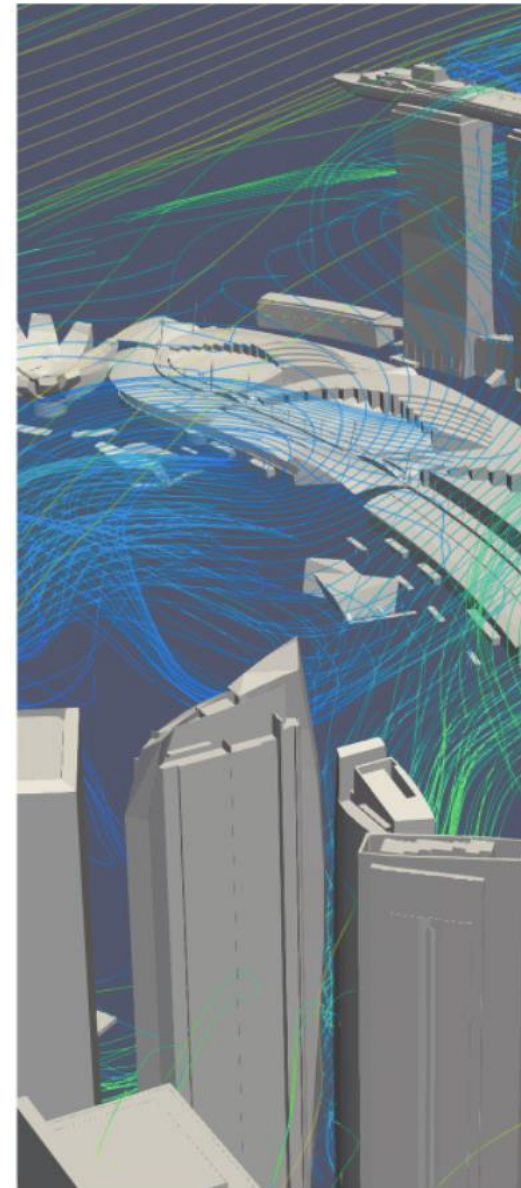
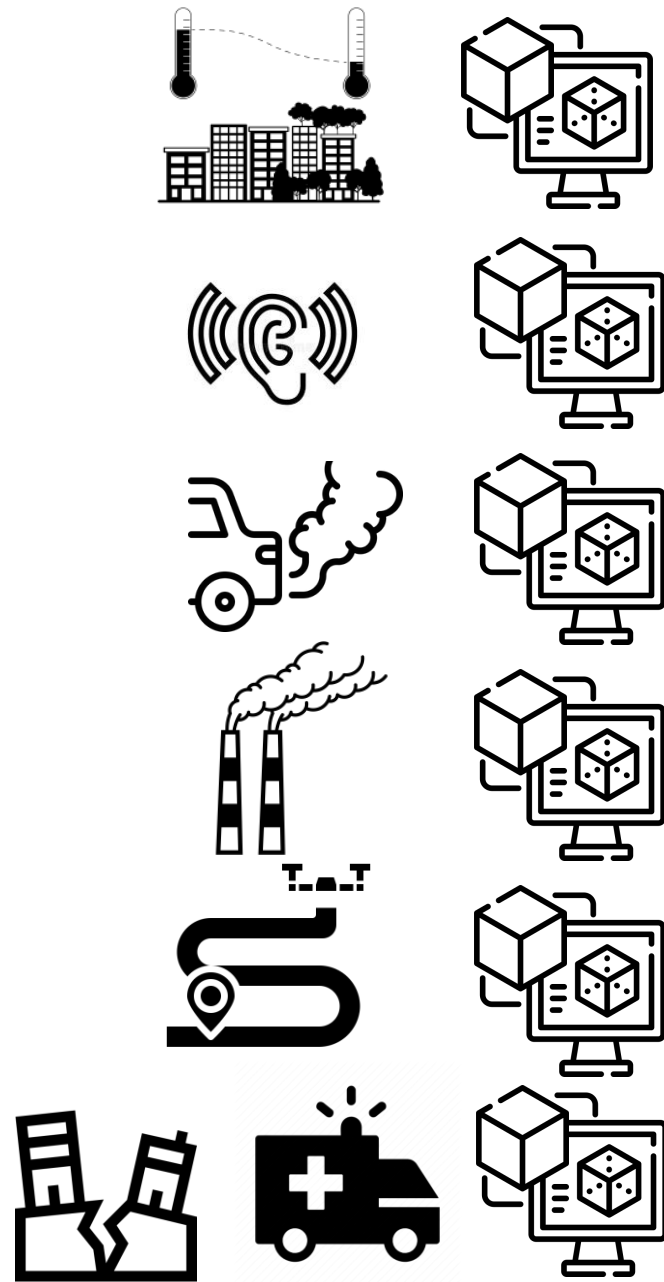
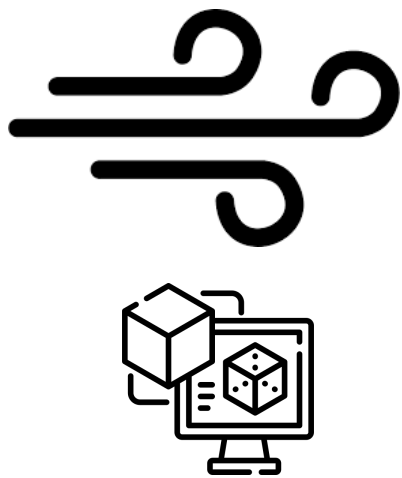
FROM RESEARCH TO APPLICATION



HYBRID TWINS

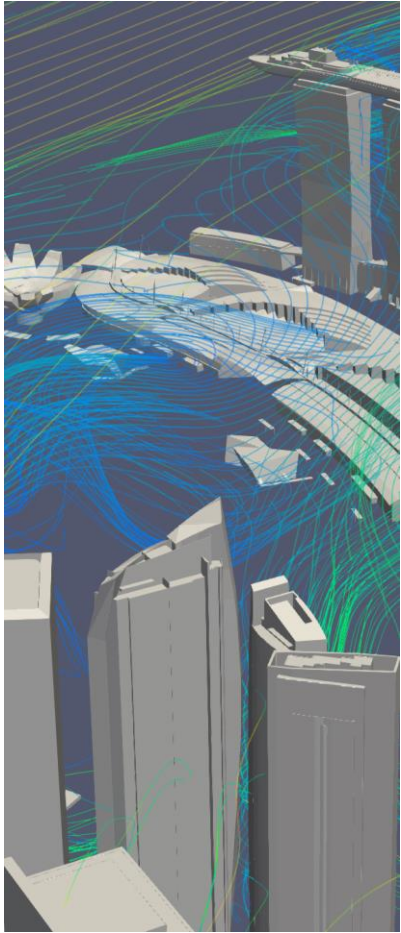


HAI BUILDER



Augmented
Marina Bay Twin

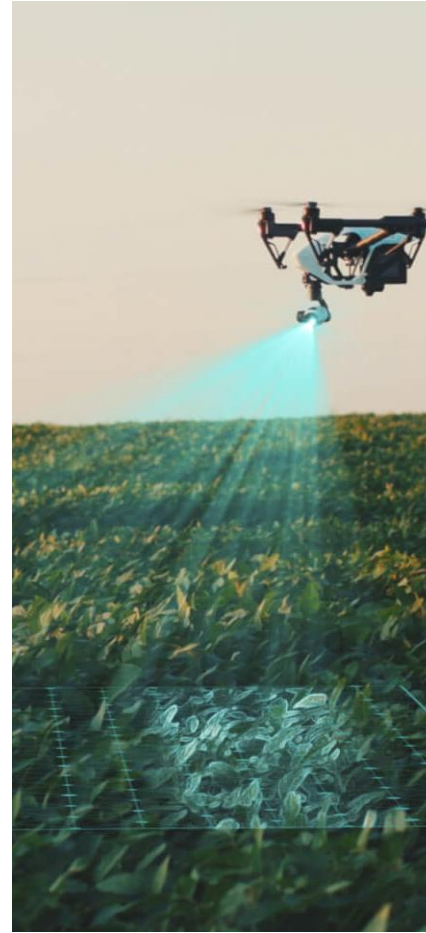
DEMONSTRATORS & USE CASES



**Augmented
Marina Bay Twin**



Digital Energy



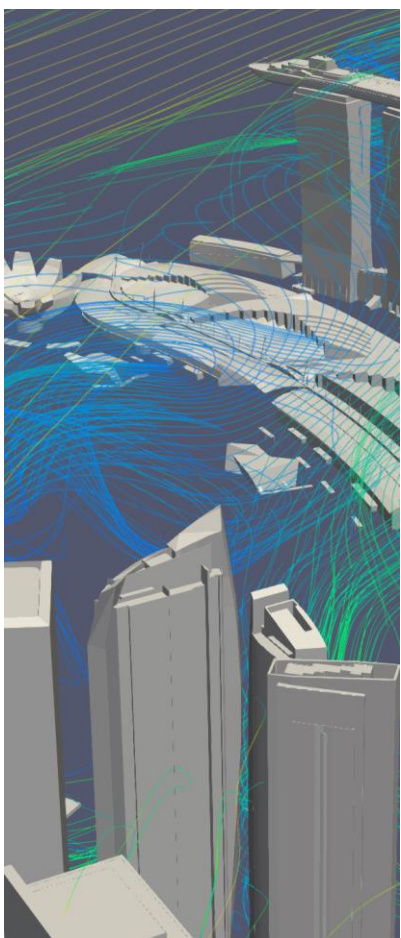
Remote Sensing



**Drone Trajectory
Planning**



**Emergency
crisis**



**Augmented
Marina Bay Twin**



Digital Energy



Remote Sensing



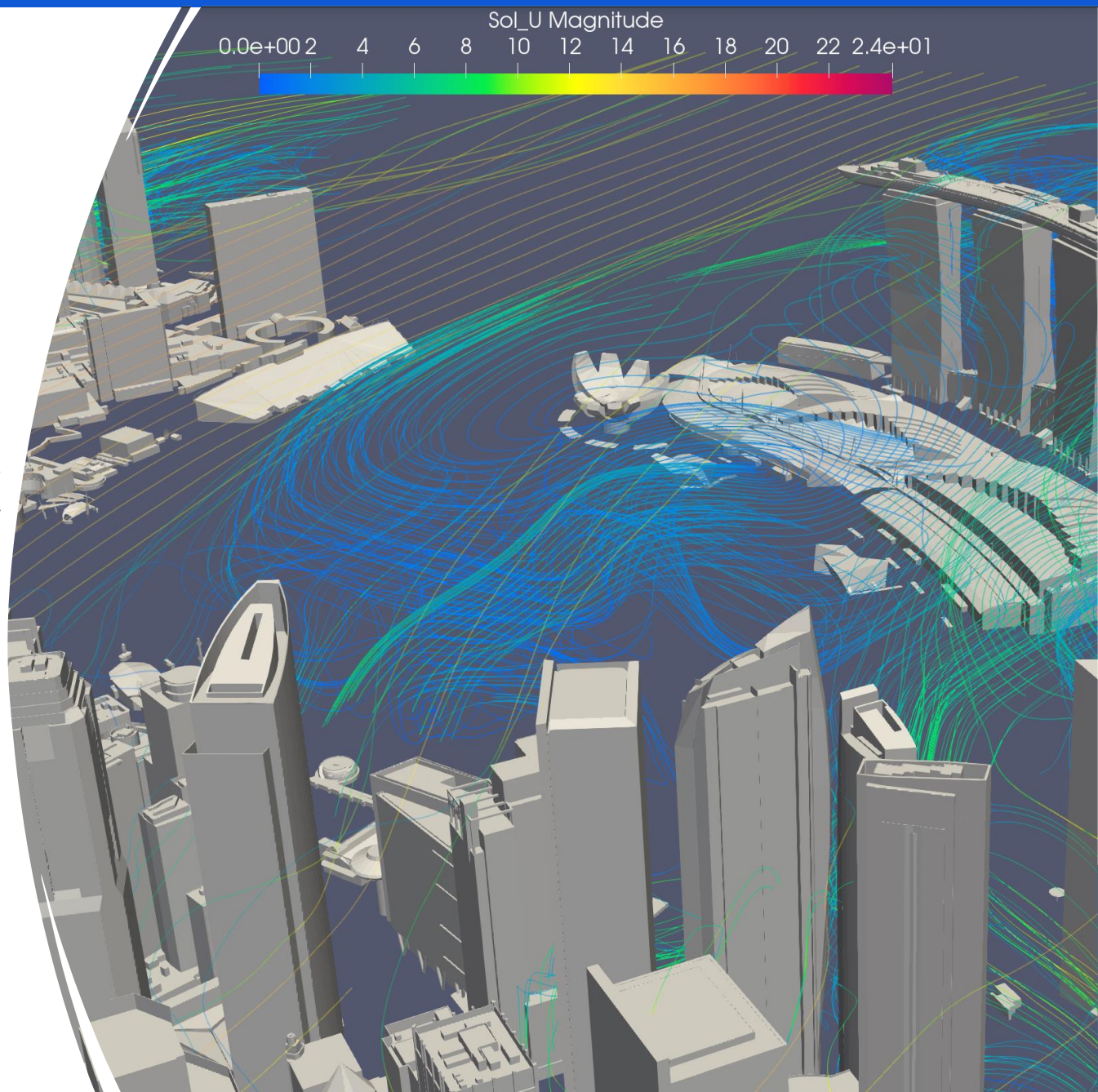
**Drone Trajectory
Planning**



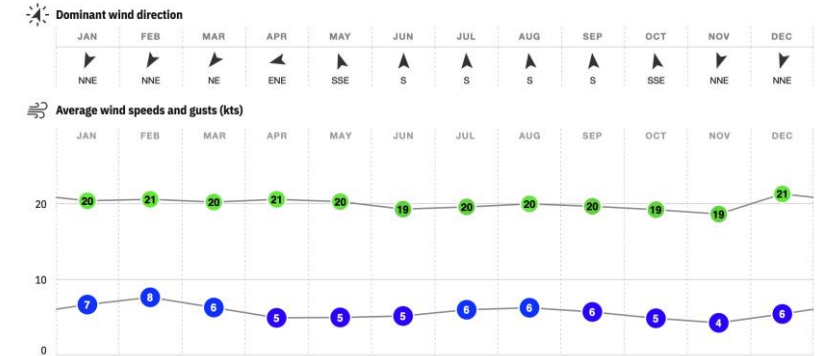
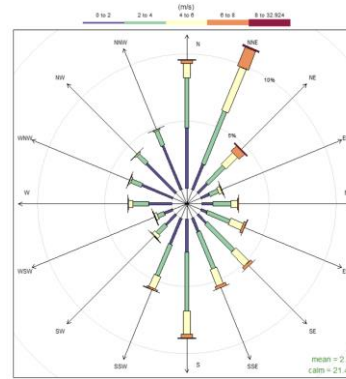
**Emergency
crisis**

Interest of having a wind map at the city level

- Inferring emissions dispersion
- Inferring air quality
- Inferring temperature and thermo-convective flows
- Drone trajectory optimal planning
- ... and many others ...

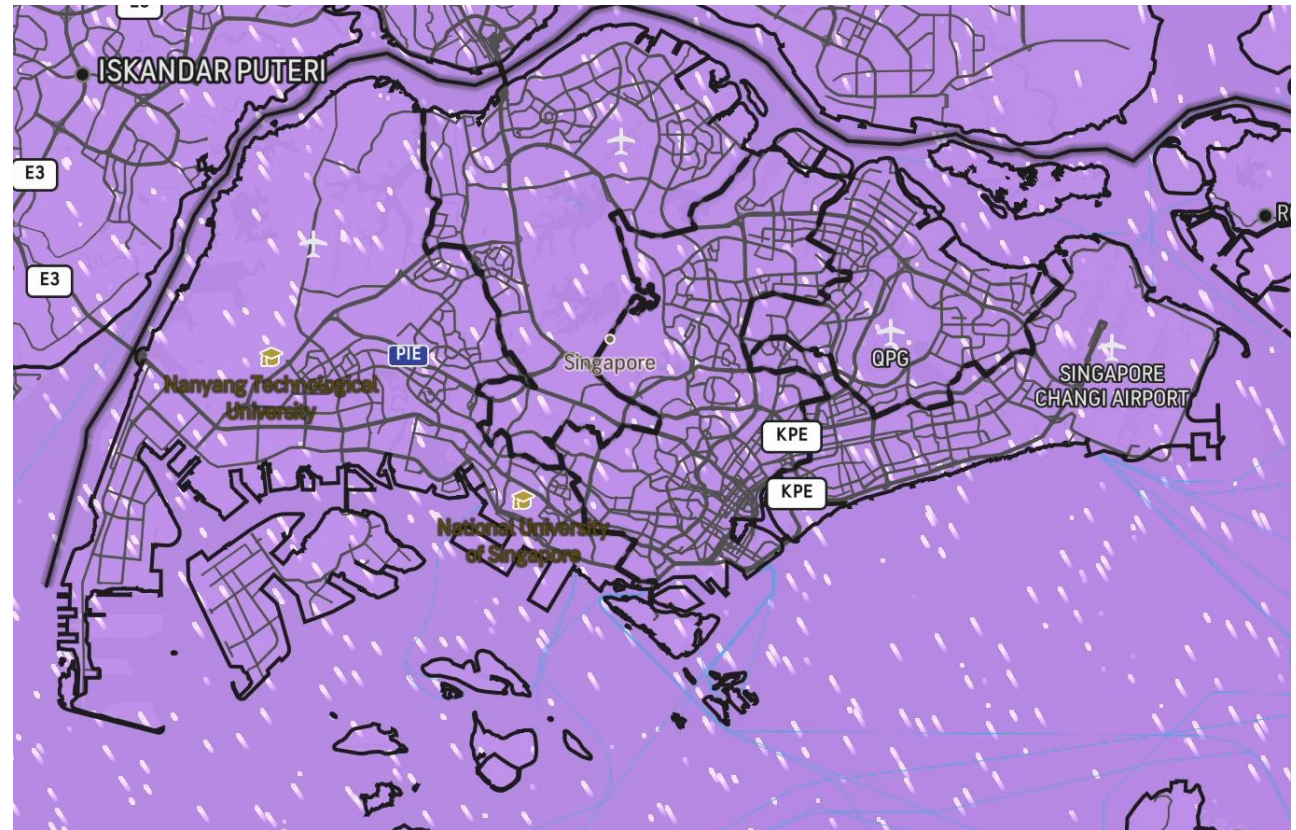


Available forecast is too coarse for providing local (street level) information on the wind velocity.



However, it provides the boundary conditions for district-level calculations

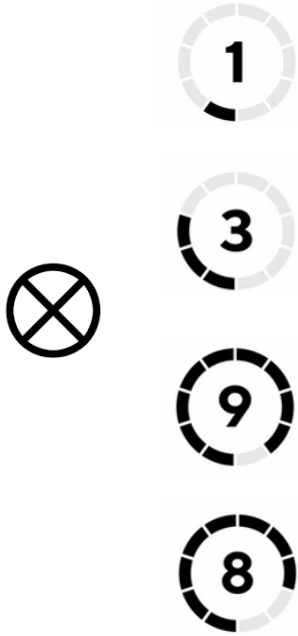
That solution is computationally too expensive



Direction



Intensity



Marina Bay Wind-map

